CART3D SIMULATIONS FOR THE 2ND AIAA SONIC BOOM PREDICTION WORKSHOP

AMS SEMINAR SERIES NASA AMES 7 SEPTEMBER 2017

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MOTIVATION



- banned over the US because of objectionable sonic boom

 Hope to overturn this with
 - Hope to overturn this with demonstrably quiet aircraft (e.g. QueSST/LBFD)

Commercial supersonic flight

- CFD tools are a major contributor to design efforts
- Sonic Boom Prediction Workshops
 - (2008) NASA FAP SBPW
 - (2014) AIAA SBPW I
 - → (2017) AIAA SBPW2



SONIC BOOM PHYSICS



Sound generated

$$\frac{\pi}{2}-\mu$$

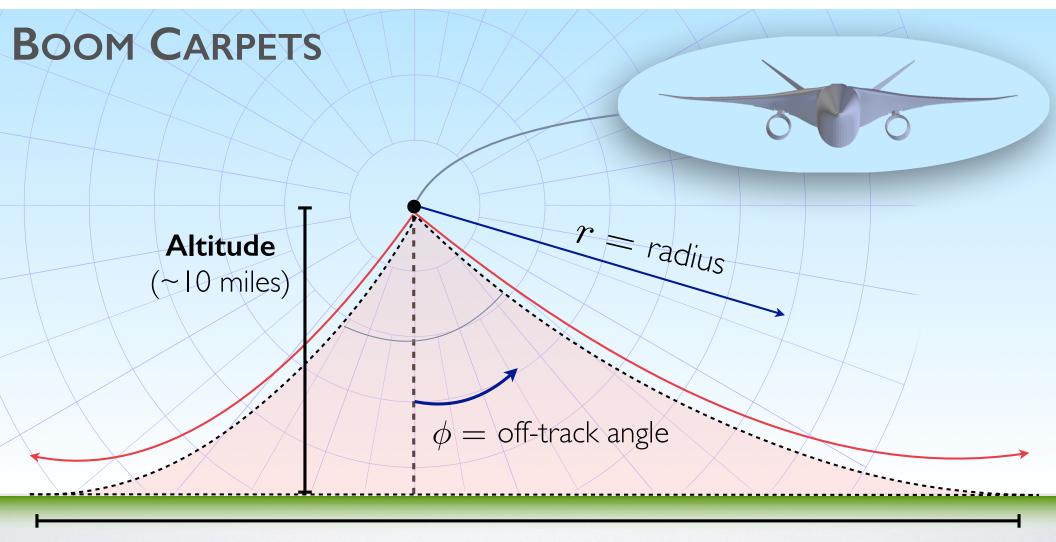
$$\mu = \sin^{-1} \left(\frac{1}{M_{\infty}} \right)$$

"Ray Path":
path of the
wave front

Refraction through atmosphere with speed of sound



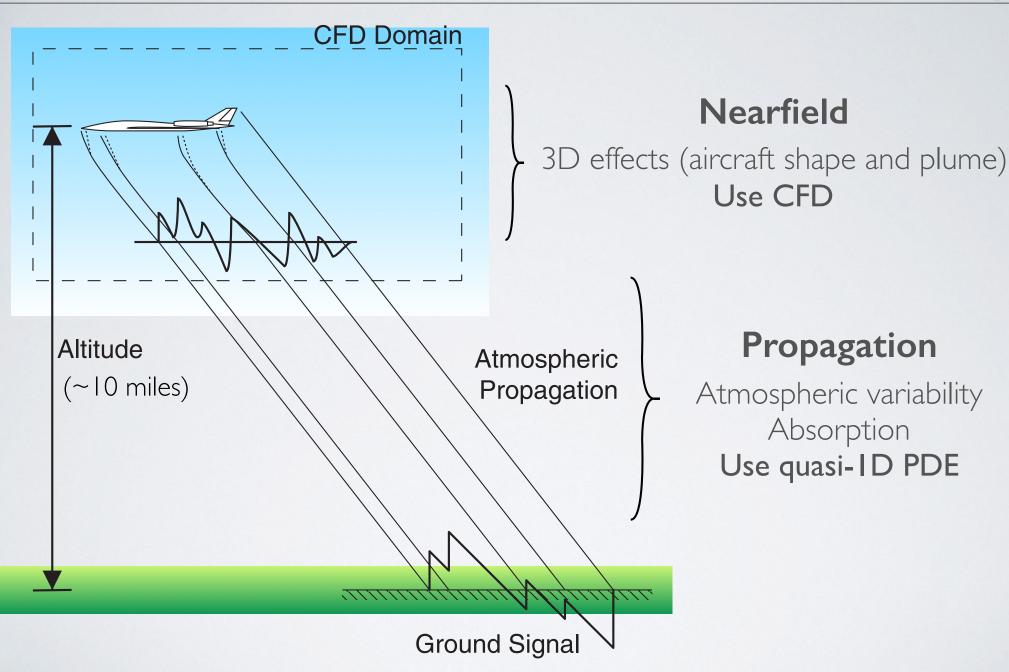
Sound heard



Track Width (70+ miles!)

SONIC BOOM PREDICTION







Workshop Results

- Nearfield (2/4 cases)
- Propagation
- Full Vehicle-to-Boom
 Simulation Path
- Conclusions

AIAA PAPER 2017-3255

Cart3D Simulations for the Second AIAA Sonic Boom Prediction Workshop

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Simulation results are presented for all test cases prescribed in the Second AIAA Sonic Boom Prediction Workshop. For each of the four nearfield test cases, we compute pressure signatures at specified distance and off-track angles, using an inviscid, embedded-boundary Cartesian-mesh flow solver with output-based mesh adaptation. The cases range in complexity from an axisymmetric body to a full low-boom sirrant configuration with a powered nacelle. For efficiency, boom carpets are decomposed into sets of independent meshes and each off-track angle is computed on a mesh with good azimuthal alignment, higher aspect ratio cells, and more tailored adaptation. The nearfield signatures generally exhibit good convergence with mesh refinement. We introduce a local error estimation procedure to highlight regions of the signatures most sensitive to mesh refinement. Results are also presented for the two propagation test cases, which investigate the effects of atmospheric profiles on ground noise. Propagation is handled with an augmented Burgers' equation method (NAAS+810OM), and ground noise metrics are computed with LCAS+

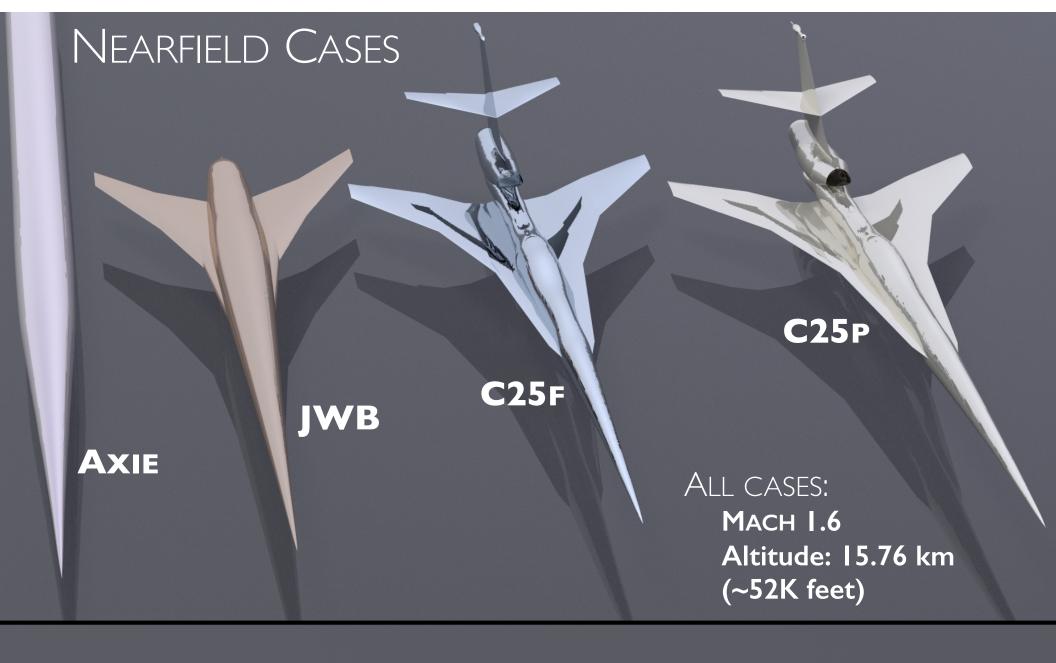
Nomenclature

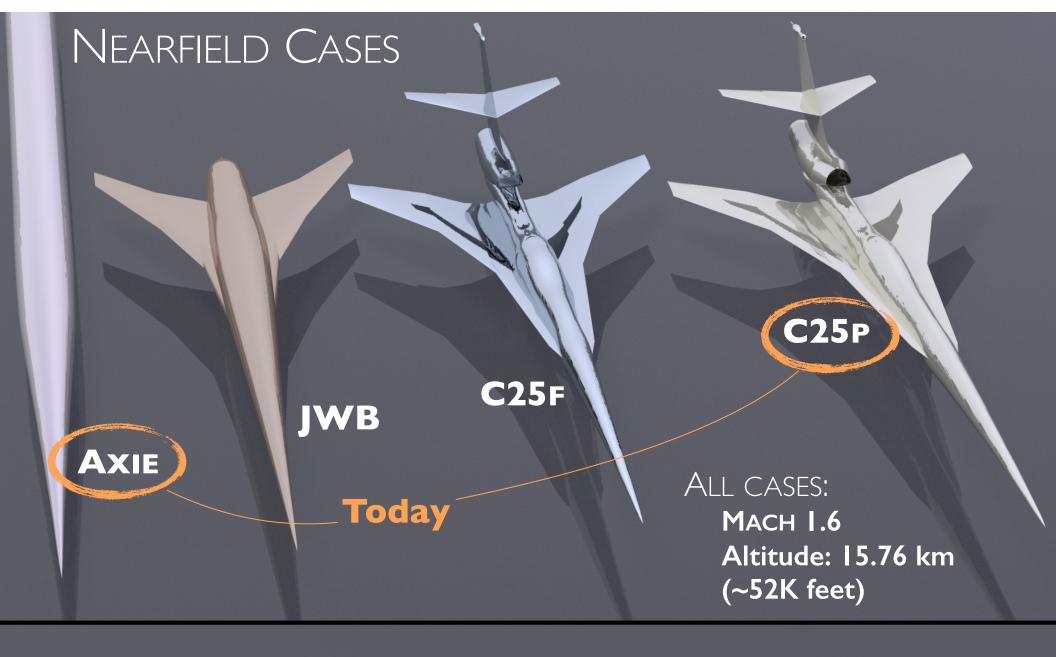
$A_{\rm ref}$	Reference area	Φ	Off-track/Azimuthal angle
$C_{D/L/M}$	Drag/lift/pitching moment coefficients	Subscrip	de
C_p	Local pressure coefficient		
e	Integrated signature differences	(·)∞	Freestream value
E	Local error estimate	(·)t	Stagnation value
J ℓ	Aerodynamic output functional	(·)c	Coarse
l	Distance along signature	(-)t	Fine
L	Reference length for propagation	(·)m	Medium
M	Mach number		
p	Static pressure	Abbreviations	
p	Order of convergence	ASEL/CSEL A-/C-weighted sound exposure level	
r	Distance from flight path	AXIE	Axisymmetric body (Case I)
T	Temperature	AXIE-PROP Axisymmetric body (Prop. Case I)	
w	Weight in functional	C25F	C25D with flow-through nacelle (Case III
α	Angle of attack	C25P	C25D with powered nacelle (Case IV)
В	$\sqrt{M_{\infty}^2 - 1}$	JWB	JAXA wing-body (Case II)
β θ	Offset angle to avoid sonic glitch	LCASB	Loudness Code for Asymmetric Sonic Boon
Į4.	Mach angle = $\sin^{-1}(1/M_{\infty})$	LM-1021	Lockheed Martin 1021 (Prop. Case II)
ρ	Density	PL	Perceived level of noise
T	Normalized x-distance from nose Mach cone	SBPW	Sonic Boom Prediction Workshop

1 of 25

American Institute of Aeronautics and Astronautics

ALL REQUIRED AND OPTIONAL CASES FROM BOTH WORKSHOPS





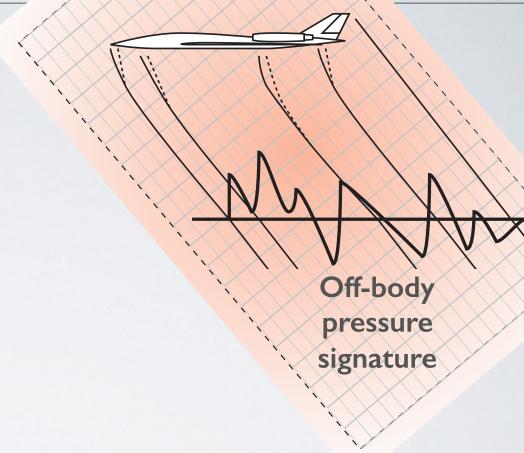
OUTLINE



- Nearfield Workshop Cart3D
 - Meshing approach Mach Alignment + Adaptation
 - Boom Carpets Azimuthal Alignment
 - **Results** for Cases 1 and 4
 - Local Error Analysis
- Propagation Workshop
- Full Vehicle-to-Boom Simulation Path
- Conclusions

CFD AND MESHING





CFD AND MESHING

NASA

Flow Solver — Cart3D VI.5

- Steady, inviscid flow
- 2nd-order upwind method
- Multigrid acceleration
- Domain decomposition highly scalable
- For this work: Barth-Jespersen limiter

Automatic Meshing

- Multilevel Cartesian mesh with embedded boundaries
- Handles arbitrarily complex vehicle shapes

Off-body pressure signature

Error Estimation and Goal-Oriented Mesh Adaptation

- Discretization error estimates computed via method of adjointweighted residuals
- Mesh automatically refined in locations with most impact on signatures





$$M_{\infty} = 1.6$$

$$\alpha = 0^{\circ}$$
 Offset to avoid "sonic glitch"

Level 0 mesh 22K cells

"sonic glitch"

Basic Meshing Approach:

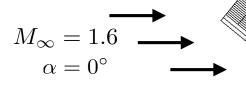
- I. Rotate mesh very close to the Mach angle
- 2. **Stretch** in the principal propagation direction
- 3. Adapt mesh to resolve line sensor outputs (method of adjoint-weighted residuals)

$$\mathcal{J}_r = \int_0^L w(\ell) \left(\frac{p(\ell) - p_{\infty}}{p_{\infty}} \right)^2 d\ell$$

r/L=5

Adaptation

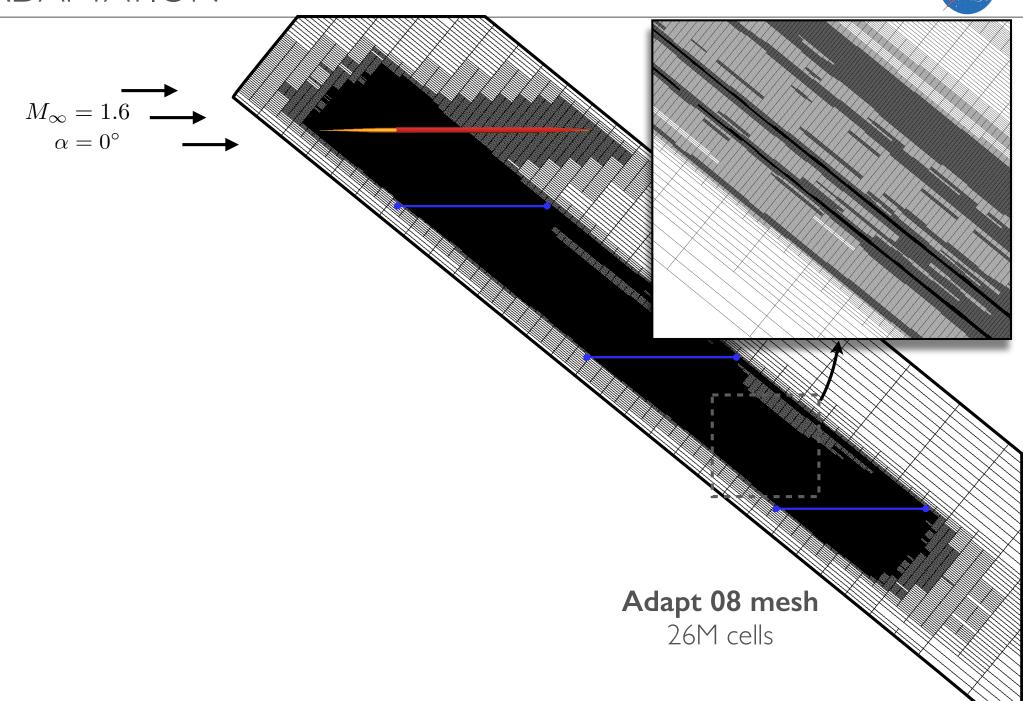






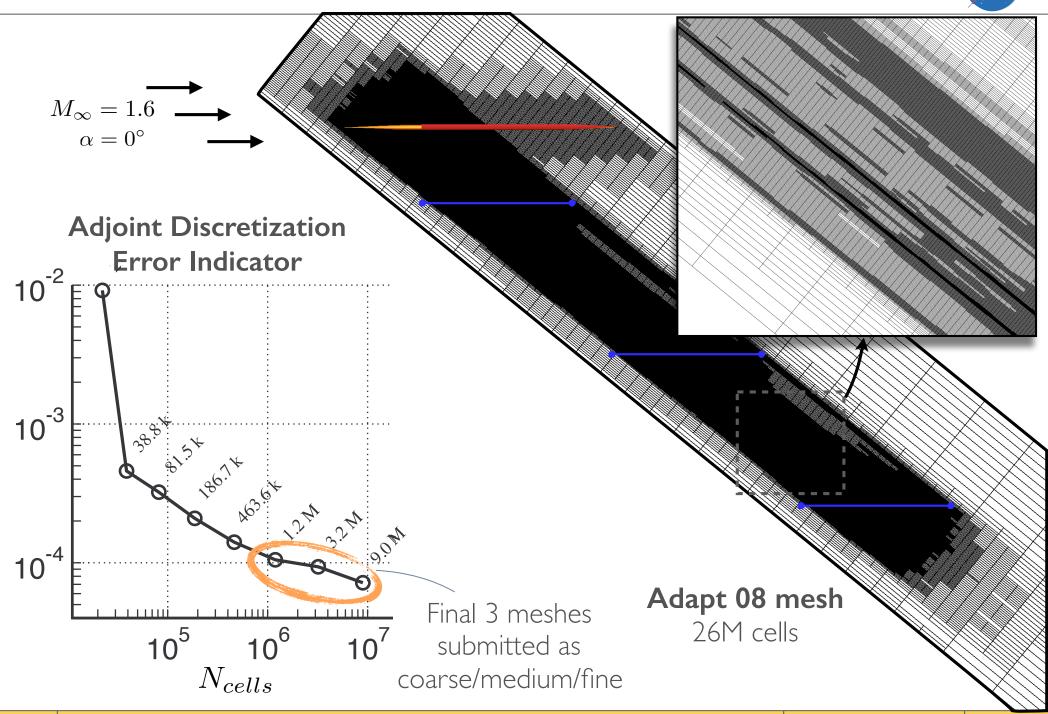
ADAPTATION





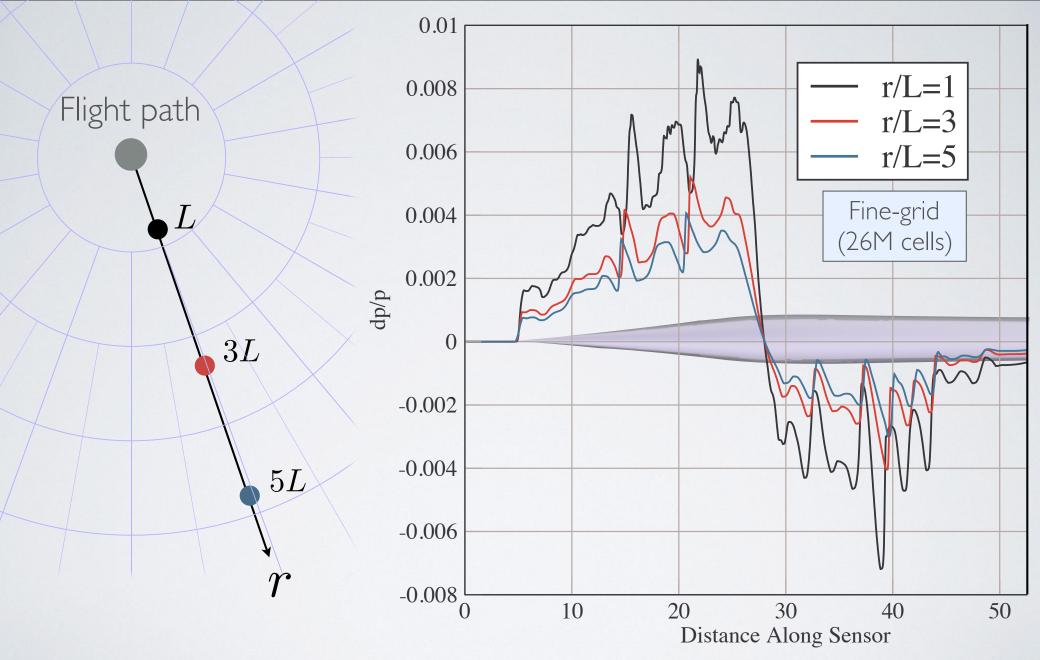
ADAPTATION





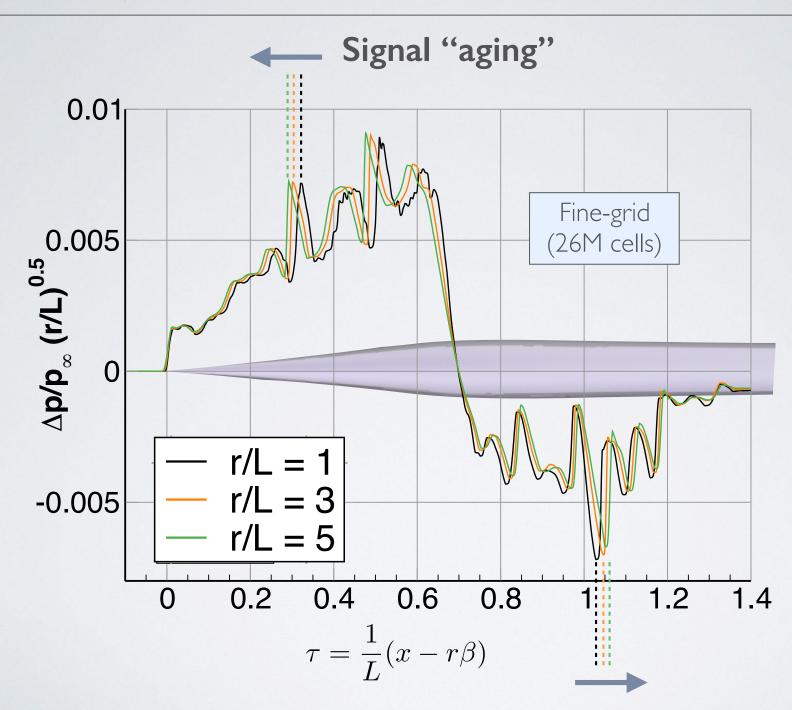
AXIE -- SIGNALS





AXIE — SIGNALS

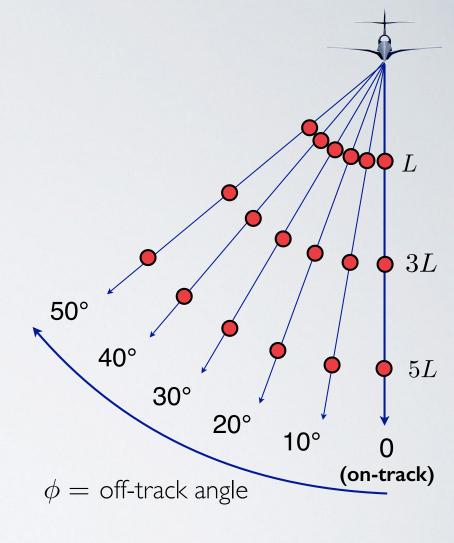




BOOM CARPETS







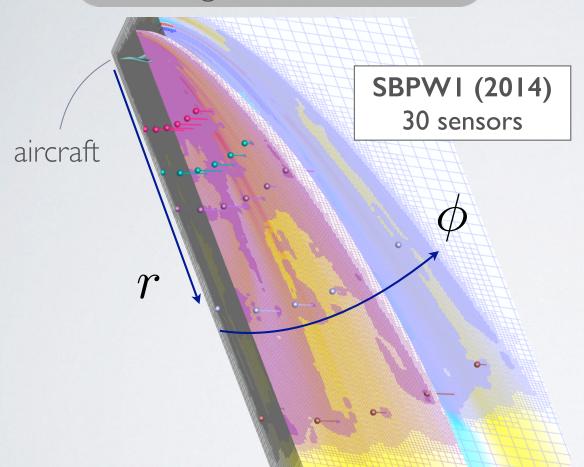
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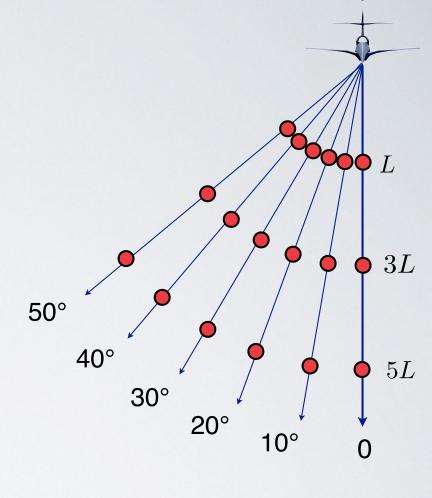
BOOM CARPETS WITH MONOLITHIC MESH



Compute entire carpet

in a single Cartesian mesh



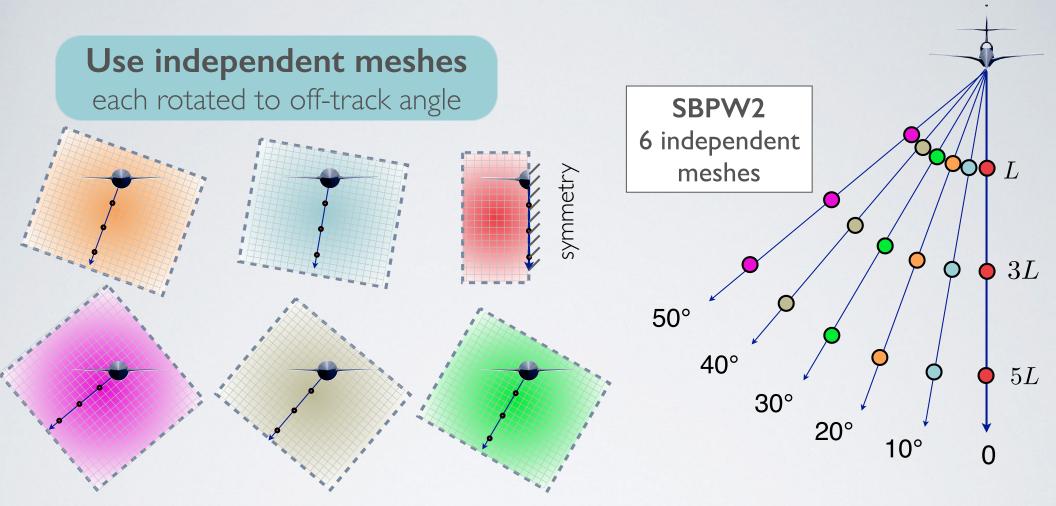


- Off-track angles are misaligned
- Aspect ratio is constrained

high cell-counts

DECOMPOSING BOOM CARPETS



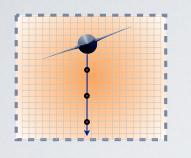


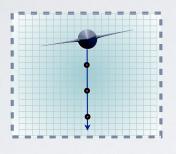
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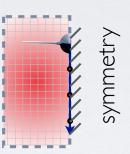


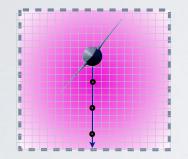
Use independent meshes

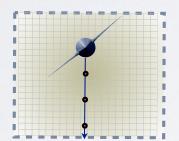
each rotated to off-track angle

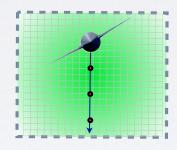


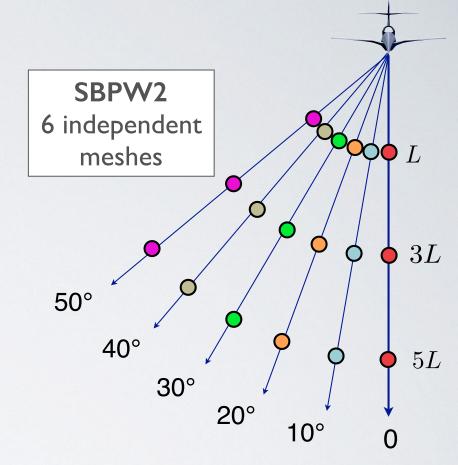










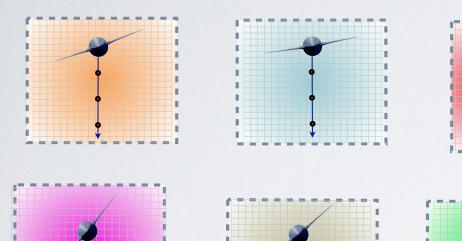


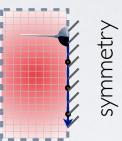
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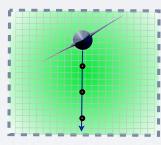


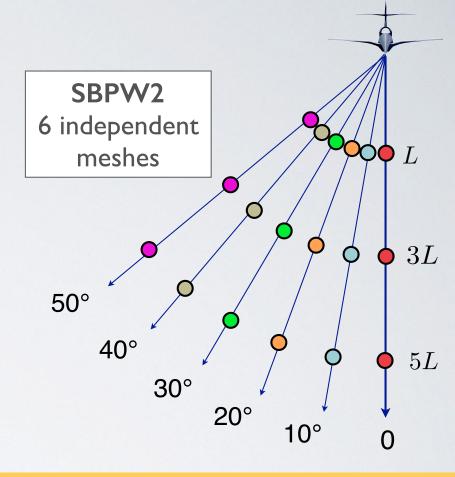
Use independent meshes

each rotated to off-track angle



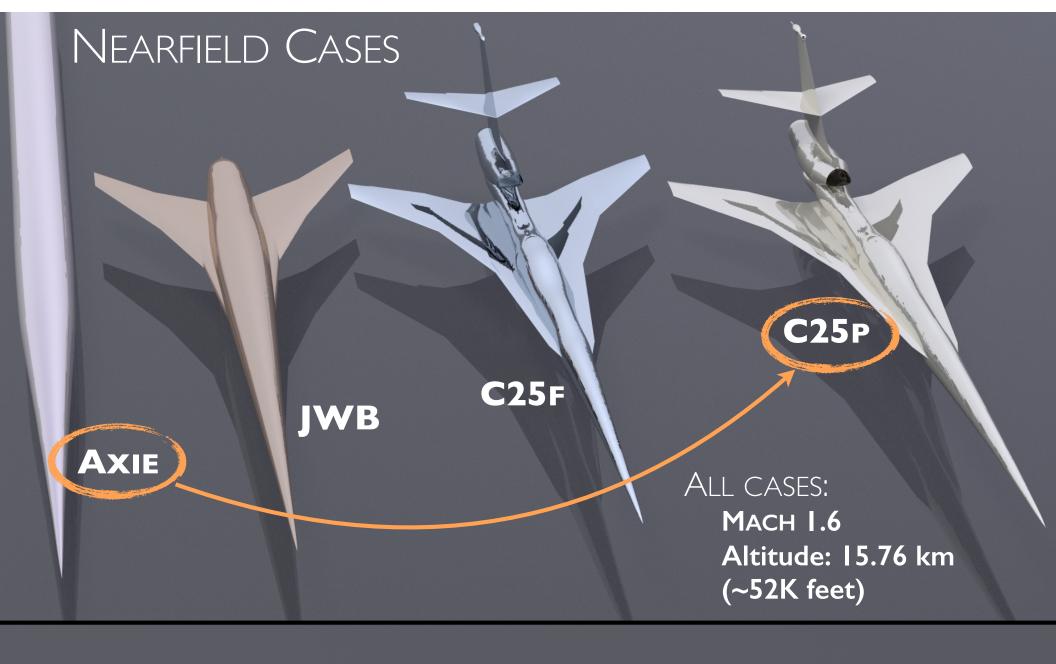






Splitting permits

- azimuthal alignment, which permits:
 - higher stretching
- Simultaneous computation of off-track angles in carpet



CONCEPT 25D

POWERED VARIANT (C25P)

Flight Conditions

Mach I.6

 $\alpha = 3.375^{\circ}$

Inlet Conditions

$$\frac{p}{p_{\infty}} = 3.26$$

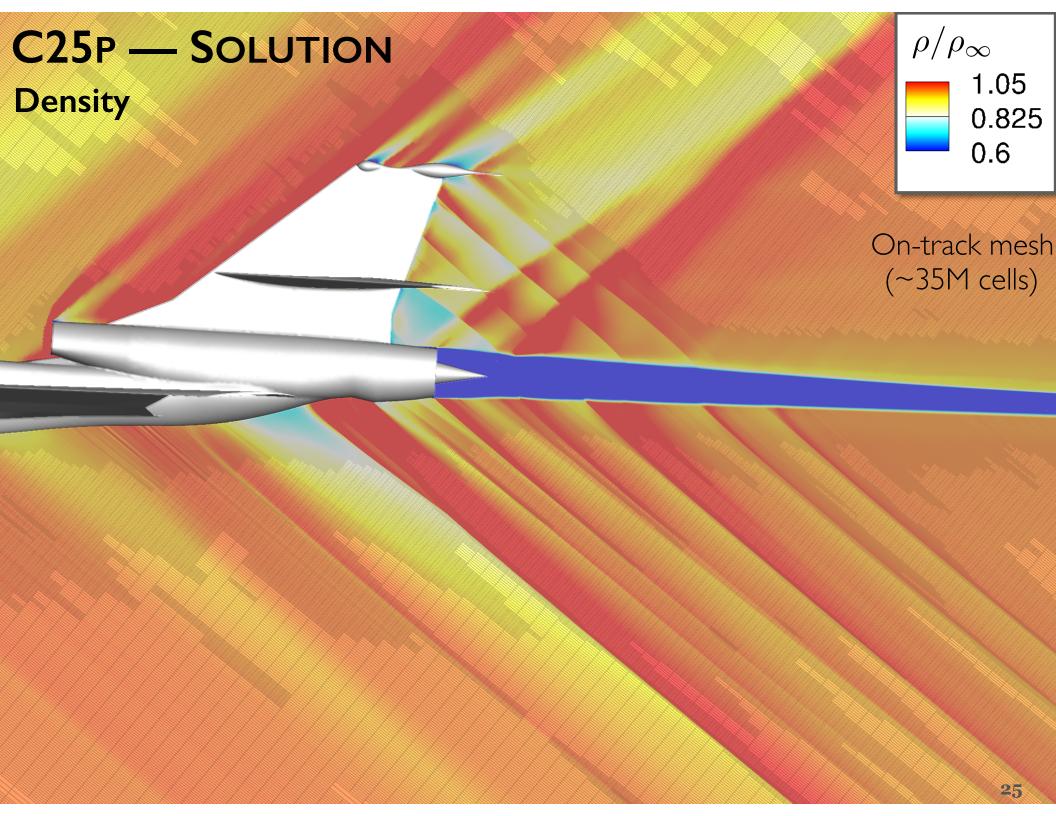
Plenum Conditions

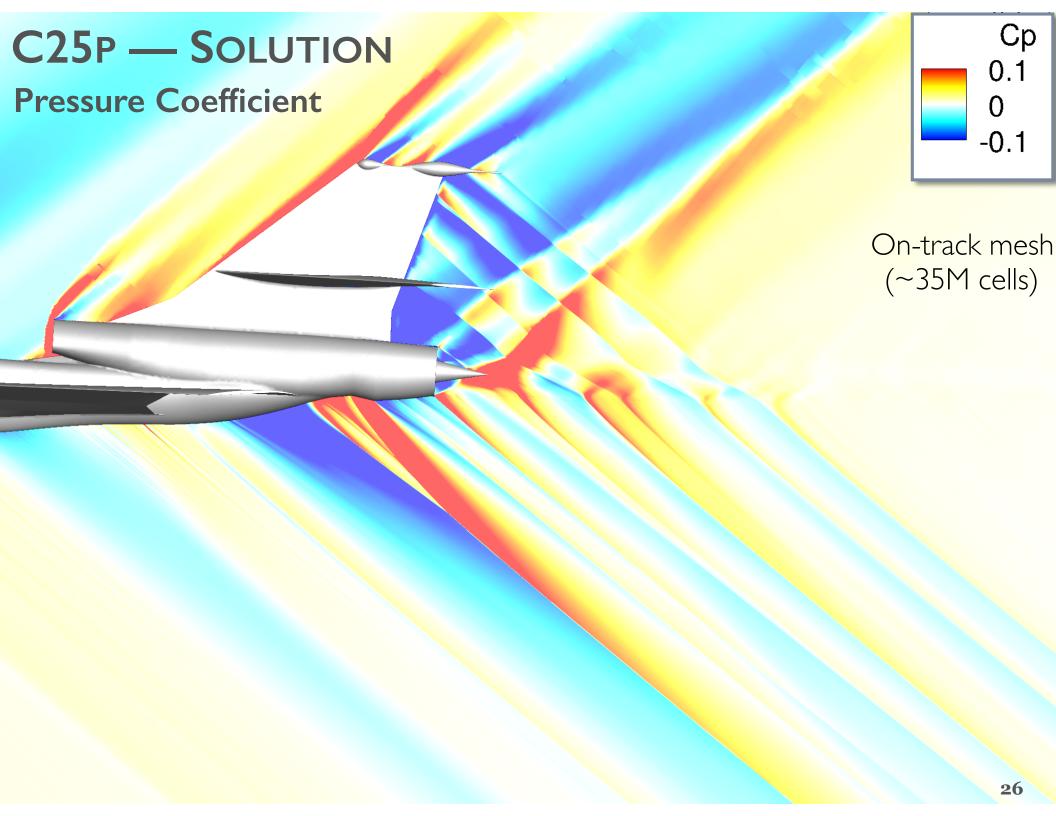
$$\frac{p_t}{p_{\infty}} = 14.54$$

$$\frac{T_t}{T_{\infty}} = 7.87$$

Plug nozzle

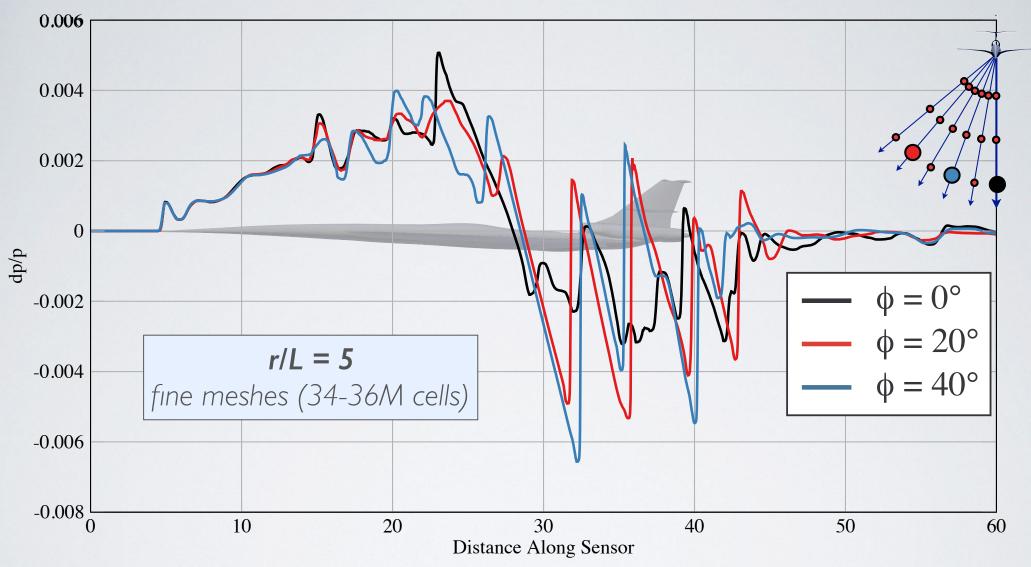
Contoured tail bulb





C25P — SIGNATURES





Each off-track angle — **35M cell mesh: 4hr 30min** on 28 cores *Includes flow solution* + *all meshing, adjoint solutions, error estimation, etc.*

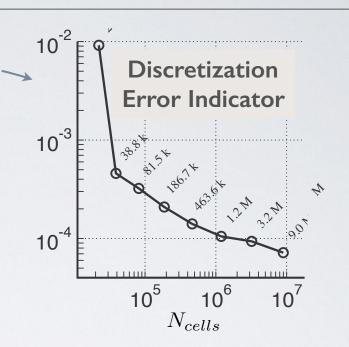
Assessing Mesh Convergence



Adjoint: Is the integrated functional converging asymptotically?

▶ Non-intuitive units on error

$$\mathcal{J}_r = \int_0^L w(\ell) \left(\frac{p(\ell) - p_{\infty}}{p_{\infty}} \right)^2 d\ell$$



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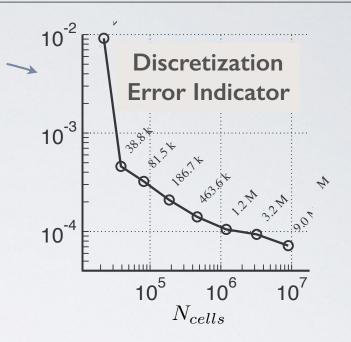
Assessing Mesh Convergence

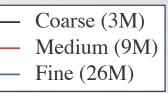


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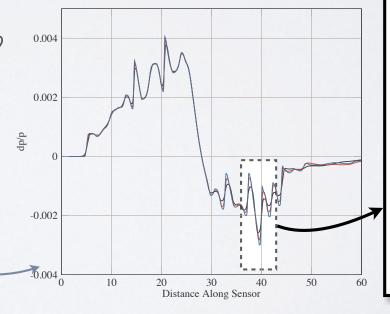
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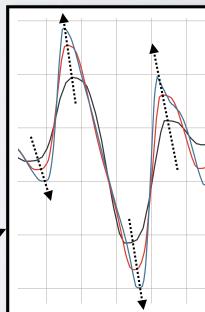




Qualitative: Are signal features converging with mesh refinement?

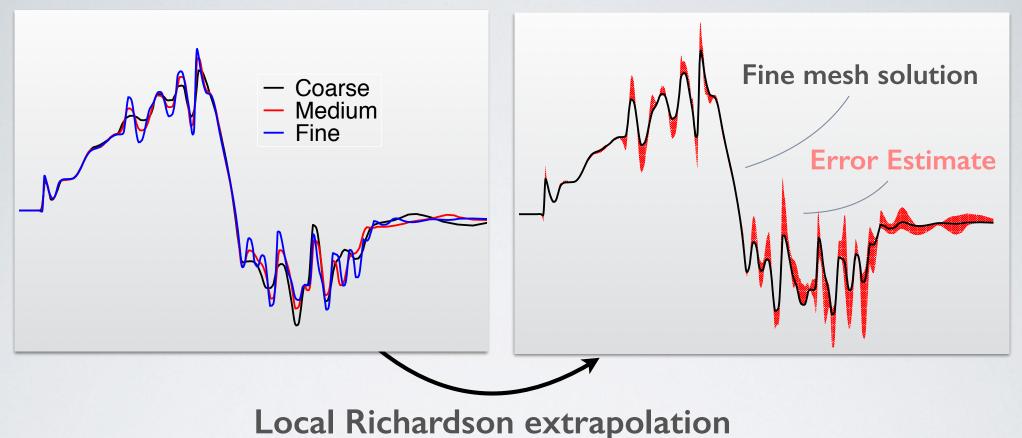
- Out of context, has no quantitative anchor, however:
- The signatures are the result of a error reducing process.





LOCAL ERROR ANALYSIS





- Incorporates estimate of global rate of convergence
- ▶ Reveals significant **local** variation in error and rate of convergence
- ▶ Can be used for any mesh refinement technique (not just adjoint-based)

Details: AIAA Paper 2017-3255

LOCAL ERROR ANALYSIS OF WORKSHOP SUBMISSIONS



Figure 10. AXIE signature computed on fine grids plotted with discretization error estimates (R = 5).



a) AA, CA, CC, FA (shown), GA, HA, IA, JA.

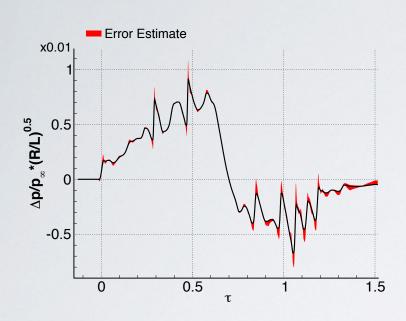
Good convergence everywhere, tight bounds [8 participants]

(2017) Park and Nemec, "Nearfield Summary and Statistical Analysis of the Second AIAA Sonic Boom Prediction Workshop"

LOCAL ERROR ANALYSIS OF WORKSHOP SUBMISSIONS

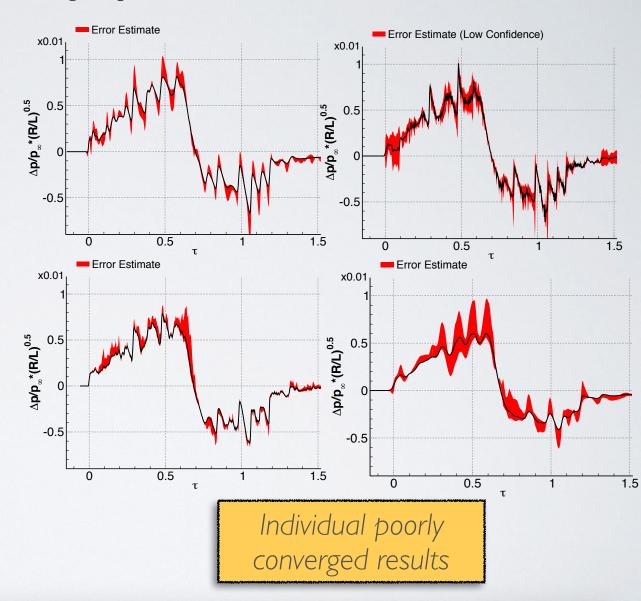


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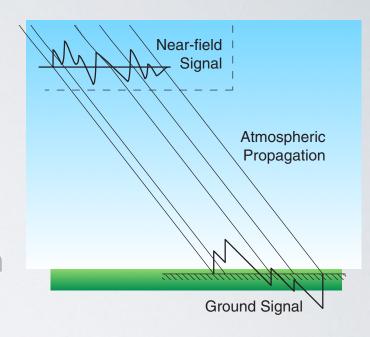


(2017) Park and Nemec, "Nearfield Summary and Statistical Analysis of the Second AIAA Sonic Boom Prediction Workshop"

OUTLINE



- √ Nearfield Workshop
- Propagation Workshop sBOOM
 - Numerical approach
 - Propagation Results
- Full Vehicle-to-Boom Simulation Path
- Conclusions

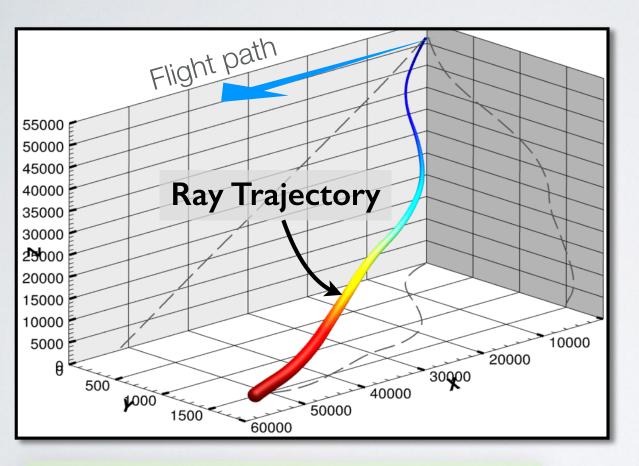


Atmospheric Propagation with sBOOM



sBOOM

- Ray-tracing
- 2. Quasi-ID, augmented Burgers' equation



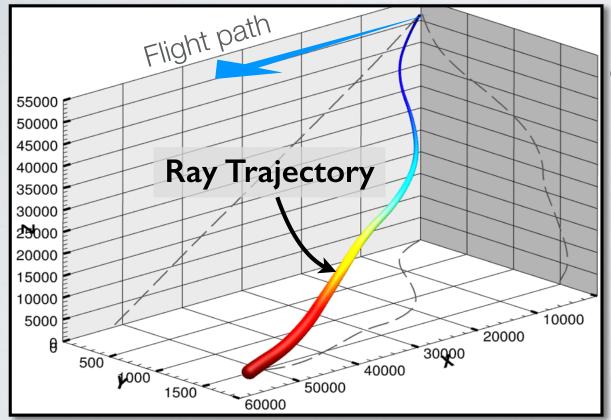
(2011) Rallabhandi, "Advanced Sonic Boom Prediction Using the Augmented Burgers Equation"

Atmospheric Propagation with sBOOM

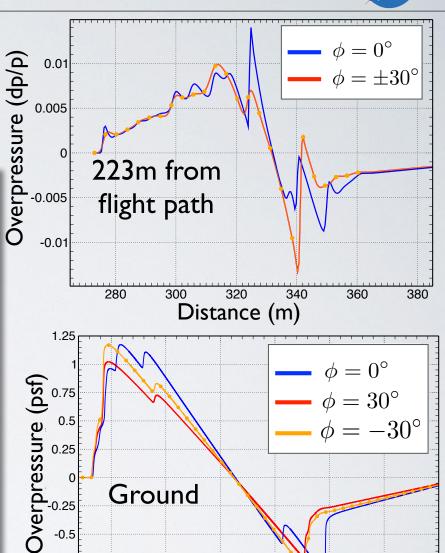


sBOOM

- Ray-tracing
- 2. Quasi-ID, augmented Burgers' equation



(2011) Rallabhandi, "Advanced Sonic Boom Prediction Using the Augmented Burgers Equation"



150

Time (ms)

100

-0.75

50

200

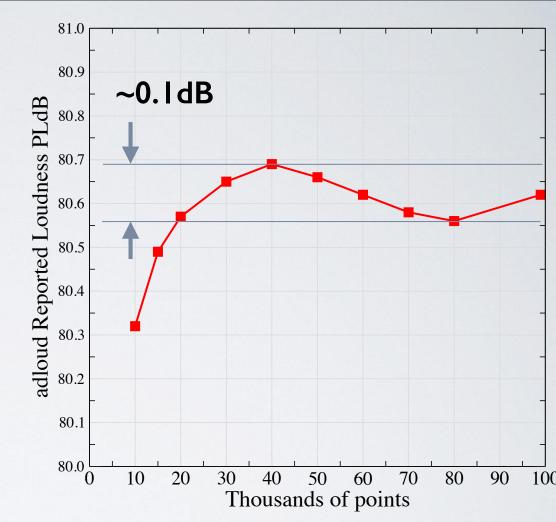
250

300

Atmospheric Propagation with sBOOM



- Discretization error
 Finite difference solution of PDE on uniform grid
- Input error
 Input ~ I 00X coarser than output
 Oversampling introduces high freq.
- Mesh refinement studies
 Numerical sources of error ~0.1dB
 (cf. atmospheric variability of ~5 dB)
 But not clearly asymptotic



PROPAGATION CASES



AXIE

Lref = 43m (141 ft)

Conditions:

 $M_{\infty} = 1.6$

Altitude = $15.8 \text{ km} (\sim 52 \text{K ft})$

Profiles:

- ISO Standard Atmosphere
- ISO Std. Atm. with 70% humidity
- Hot day, coastal Virginia
- Hot dry day, Edwards AFB

LM-1021



Conditions:

 $M_{\infty} = 1.6$

Lref = 71m (233 ft)

from SBPWI (2014)

Altitude = $16.7 \text{ km} (\sim 55 \text{K ft})$

Profiles:

- ISO Standard Atmosphere
- ISO Std. Atm. with 70% humidity
- 2 consecutive winter days in Green Bay, WI

BOOM FOOTPRINT



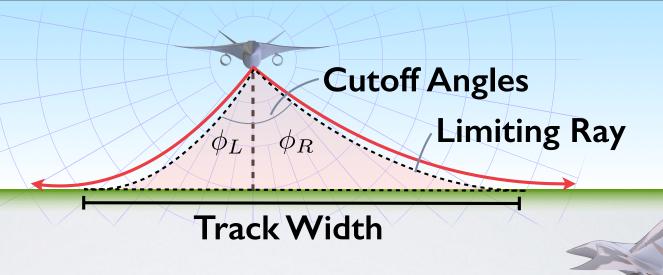
Cutoff Angles ϕ_R Limiting Ray



LM-1021	Cutoff		
Std. Atm	±50°		
Atm # 1	-74°	57°	
Atm # 2	-59°	65°	

BOOM FOOTPRINT





AXIE	Cutoff		Track Width
Std. Atm	±50°		69 km
Atm # 3	-53°	50°	85 km
Atm # 4	-44°	47°	72 km

LM-1021	Cutoff		Track Width	
Std. Atm	±50°		71 km	
Atm # 1	-74°	57°	87 km	
Atm # 2	-59°	65°	111 km	

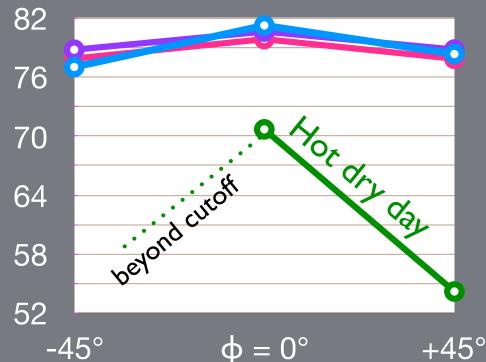
LOUDNESS

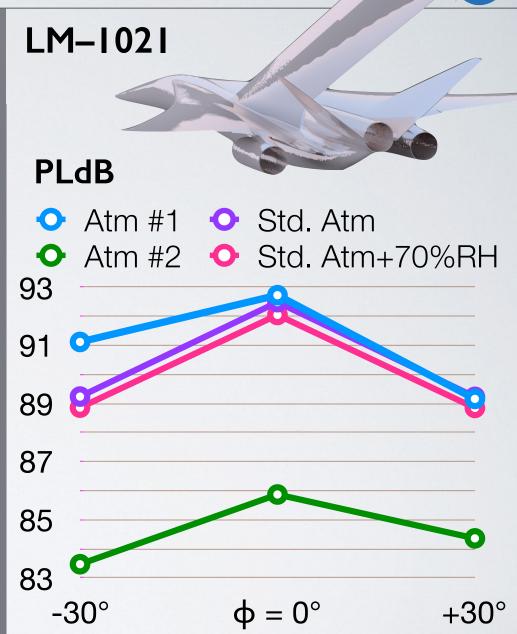


AXIE

PLdB*

- Atm #3 Std. Atm
- Atm #4 Std. Atm+70%RH





*(1991) Shepherd & Sullivan, "A Loudness Calculation Procedure Applied to Shaped Sonic Booms"

OUTLINE



- √ Nearfield Workshop
- ✓ Propagation Workshop sBOOM
- Full Vehicle-to-Boom Simulation Path
 - Propagate nearfield CFD signatures through standard atmosphere
 - Overall convergence and accuracy
- Conclusions

NEARFIELD + PROPAGATION



Perceived loudness (PLdB)

from r/L=5 on fine CFD mesh

Case	$\Phi = 0^{\circ}$	$\Phi = 10^{\circ}$	$\Phi = 20^{\circ}$	$\Phi = 30^{\circ}$	$\Phi = 40^{\circ}$	$\Phi = 50^{\circ}$
AXIE	78.1	<u> </u>	_		_	_
JWB	79.5	76.5	78.2	82.2	81.6	76.6
C25F	78.1	80.4	80.1	82.2	80.1	73.3
C25P	80.4	81.3	78.3	81.4	78.7	73.3

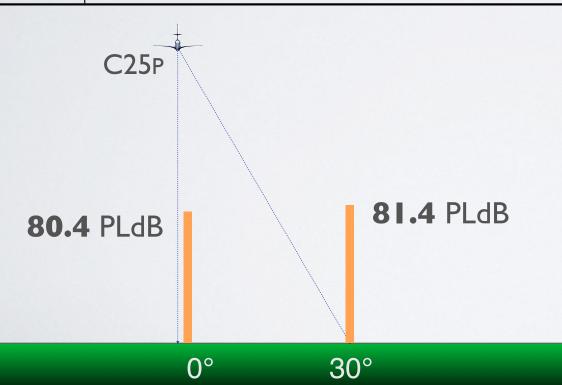
NEARFIELD + PROPAGATION



Perceived loudness (PLdB)

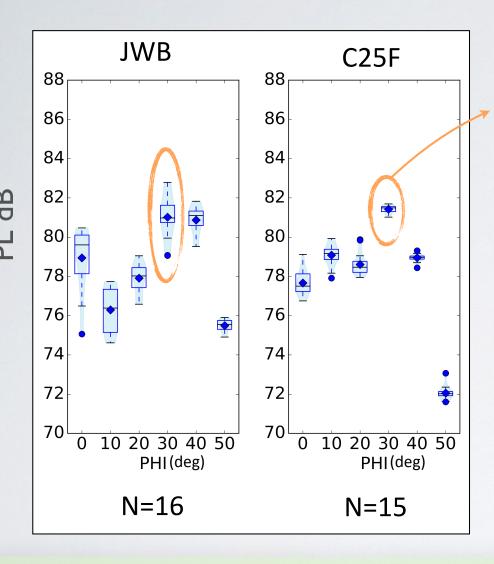
from r/L=5 on fine CFD mesh

Case	$\Phi = 0^{\circ}$	$\Phi = 10^{\circ}$	$\Phi = 20^{\circ}$	$\Phi = 30^{\circ}$	$\Phi = 40^{\circ}$	$\Phi = 50^{\circ}$
AXIE	78.1	<u> </u>	_	_	_	<u></u>
JWB	79.5	76.5	78.2	82.2	81.6	76.6
C25F	78.1	80.4	80.1	82.2	80.1	73.3
C25P	80.4	81.3	78.3	81.4	78.7	73.3



COMPARISON



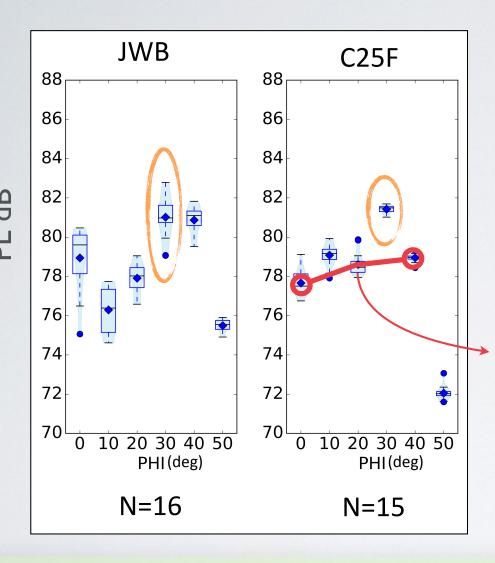


Off-track boom is not just relevant, but critical!

(2017) Park and Nemec, "Nearfield Summary and Statistical Analysis of the Second AIAA Sonic Boom Prediction Workshop"

COMPARISON





Off-track boom is not just relevant, but critical!

A coarser carpet discretization ($\Delta \Phi = 20^{\circ}$) would have under-predicted the worst boom by ~3 dB!

(2017) Park and Nemec, "Nearfield Summary and Statistical Analysis of the Second AIAA Sonic Boom Prediction Workshop"

CFD MESH CONVERGENCE OF LOUDNESS



Perceived loudness (PLdB)

from r/L=5 on fine CFD mesh

Case	$\Phi = 0^{\circ}$	$\Phi = 10^{\circ}$	$\Phi = 20^{\circ}$	$\Phi = 30^{\circ}$	$\Phi = 40^{\circ}$	$\Phi = 50^{\circ}$
AXIE	78.1 (0.4)		<u></u> -	_ 1	_	
JWB	79.5 (<mark>0.6</mark>)	76.5 (0.7)	$78.2 \ (\ 0.4)$	82.2 (1.5)	81.6 (0.1)	$76.6 \ (0.5)$
C25F	78.1 (0.8)	80.4 (0.6)	80.1 (0.1)	82.2 (0.8)	80.1 (<mark>0.6</mark>)	$73.3 \ (0.0)$
C25P	80.4 (0.5)	81.3 (0.5)	78.3 (0.3)	$81.4 \ (0.6)$	78.7 (<mark>0.4</mark>)	73.3 (1.6)

DPLdB from coarse to fine CFD mesh

Typically < I dB change from coarse to fine CFD mesh (max 1.6 dB)

CFD MESH CONVERGENCE OF LOUDNESS



Perceived loudness (PLdB)

from r/L=5 on fine CFD mesh

Case	$\Phi=0^{\circ}$	$\Phi = 10^{\circ}$	$\Phi=20^{\circ}$	$\Phi = 30^{\circ}$	$\Phi = 40^{\circ}$	$\Phi = 50^{\circ}$
AXIE	78.1 (0.4)	_	<u></u>	_	_	
JWB	79.5 (0.6)	76.5 (0.7)	$78.2 \ (0.4)$	82.2 (1.5)	81.6 (0.1)	$76.6 \ (0.5)$
				82.2 (0.8)		
C25P	80.4 (0.5)	81.3 (0.5)	78.3 (0.3)	81.4 (0.6)	78.7 (<mark>0.4</mark>)	73.3 (1.6)

\Delta PLdB from coarse to fine CFD mesh

- Typically < I dB change from coarse to fine CFD mesh (max I.6 dB)
- Most do not demonstrate **asymptotic** convergence.
- Summary results indicate similar behavior across many codes

CFD functional
$$\mathcal{J}_r = \int_0^L w(\ell) \left(\frac{p(\ell) - p_{\infty}}{p_{\infty}}\right)^2 d\ell$$

used as a convenient surrogate for loudness

FUTURE WORK



Improving CFD/Propagation Coupling

- Better understanding the CFD meshing requirements
- Using noise sensitivities to guide CFD mesh adaptation (direct adaptation to noise vs. surrogate functionals)
- Better interpolation/transfer of signatures

Physics

- Wake unsteadiness
- Maneuver, elastic effects, control surfaces
- Propagation secondary booms, reflections

HIGHLIGHTS



Nearfield with Cart3D

- Improved efficiency by carpet splitting, azimuthal alignment, and stretching
- Method for assessing local signature mesh convergence [scripts available]



HIGHLIGHTS



Nearfield with Cart3D

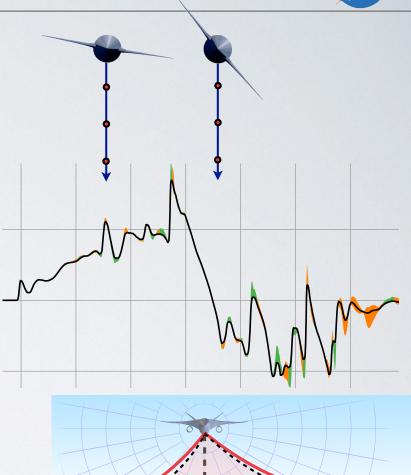
- Improved efficiency by carpet splitting, azimuthal alignment, and stretching
- Method for assessing local signature mesh convergence [scripts available]

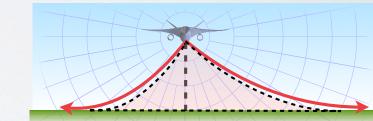
Propagation with sBOOM

- Major atmospheric variability: 2-5 dB typical, 10-20 dB in extreme cases.
- With cross-wind, 75° off-track can hit ground, track widths widen by 50%

Full Boom Simulation Path

Need to better understand asymptotic convergence of noise







QUESSTIONS?



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Supported by NASA ARMD CST Project